

A#3. Solns

1.  $f(x, y, z) = (x^2y, y^4, \frac{xz}{2} + y)$

Fixed pts:

$$\begin{cases} x^* = x^{*2}y^* & \dots \dots \dots (1) \\ y^* = y^{*4} & \dots \dots \dots (2) \\ z^* = \frac{x^*z^*}{2} + y^* & \dots \dots \dots (3) \end{cases}$$

By (2) we have

$y^* = 0$  or  $y^{*3} = 1 \Rightarrow y^* = 1.$

If  $y^* = 0$  then by (1) we have  $x^* = 0$  and by (3) we have  $z^* = 0.$

If  $y^* = 1$ , then by (1) we have

$x^* = x^{*2}$  or  $x^* = 0$  or  $x^* = 1.$

If  $x^* = 0$  then by (3) we have

$z^* = y^* = 1.$

If  $x^* = 1$  then by (3) we have

$z^* = \frac{z^*}{2} + y^*$  or  $z^* = \frac{z^*}{2} + 1$  or  $z^* = 2.$

So the fixed points are:

$$(0, 0, 0); (0, 1, 1); (1, 1, 2)$$

Stability

$$Df(x, y, z) = \begin{bmatrix} \frac{\partial f_1}{\partial x} & \frac{\partial f_1}{\partial y} & \frac{\partial f_1}{\partial z} \\ \frac{\partial f_2}{\partial x} & \frac{\partial f_2}{\partial y} & \frac{\partial f_2}{\partial z} \\ \frac{\partial f_3}{\partial x} & \frac{\partial f_3}{\partial y} & \frac{\partial f_3}{\partial z} \end{bmatrix}$$

where  $f_1 = x^2y$ ,  $f_2 = y^4$ ,  $f_3 = \frac{xz}{2} + y$ . This gives us

$$Df(\vec{x}) = \begin{bmatrix} 2xy & x^2 & 0 \\ 0 & 4y^3 & 0 \\ \frac{z}{2} & 1 & \frac{x}{2} \end{bmatrix}$$

We evaluate this matrix at each steady state & find the eigenvalues.

Stability of fixed point (0,0,0).

$$Df(2,0,0) = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

eigenvalues:  $\lambda_1 = \lambda_2 = \lambda_3 = 0$

$\therefore |\lambda_i| < 1$  and (0,0,0) is a sink.

Stability of fixed point (0,1,1):

$$Df(0,1,1) = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 4 & 0 \\ \frac{1}{2} & 1 & 0 \end{bmatrix}$$

eigenvalues:  $\lambda_1 = \lambda_2 = 0, \lambda_3 = 4$

$\therefore |\lambda_1| = |\lambda_2| = 0 < 1, \text{ + } |\lambda_3| > 1,$

so (0,1,1) is a saddle.

Stability of fixed point (1,1,2):

$$Df(1,1,2) = \begin{bmatrix} 2 & 1 & 0 \\ 0 & 4 & 0 \\ 1 & 1 & \frac{1}{2} \end{bmatrix}$$

eigenvalues:  $\lambda_1 = 2, \lambda_2 = 4, \lambda_3 = \frac{1}{2}$

$\therefore |\lambda_1| > 1 + |\lambda_2| > 1, + |\lambda_3| < 1$

So (1,1,2) is a saddle.

2.  $f(x,y) = (ax - bx^2, x^2 + 2y)$

a)  $a=4, b=1$

let us write the given period-2 orbit as

$$\left\{ \vec{p}_1, \vec{p}_2 \right\} = \left\{ \left( \frac{5+\sqrt{5}}{2}, -\frac{15}{2} - \frac{5\sqrt{5}}{6} \right), \left( \frac{5-\sqrt{5}}{2}, -\frac{15}{2} + \frac{5\sqrt{5}}{6} \right) \right\}.$$

(5)

& if the given points do indeed form a period-2 orbit, then we should find that  $f(\vec{p}_1) = \vec{p}_2 + f(\vec{p}_2) = \vec{p}_1$ .

### Verification

$$f(\vec{p}_1) = \left( 4 \frac{(5+\sqrt{5})}{2} - \left[ \frac{(5+\sqrt{5})}{2} \right]^2, \left[ \frac{(5+\sqrt{5})}{2} \right]^2 + 2 \left( \frac{-15}{2} - \frac{5\sqrt{5}}{6} \right) \right)$$

$$= \left( \frac{40 + 8\sqrt{5} - (25 + 10\sqrt{5} + 5)}{4}, \frac{25 + 10\sqrt{5} + 5}{4} - 15 - \frac{5\sqrt{5}}{3} \right)$$

$$= \left( \frac{10 - 2\sqrt{5}}{4}, \frac{15 + 5\sqrt{5}}{2} - 15 - \frac{5\sqrt{5}}{3} \right)$$

$$= \left( \frac{5 - \sqrt{5}}{2}, -\frac{15}{2} + \frac{15\sqrt{5} - 10\sqrt{5}}{6} \right)$$

$$= \left( \frac{5 - \sqrt{5}}{2}, -\frac{15}{2} + \frac{5\sqrt{5}}{6} \right) = \vec{p}_2$$

$$f(\vec{p}_2) = \left( 4 \frac{(5-\sqrt{5})}{2} - \frac{(5-\sqrt{5})^2}{4}, \frac{(5-\sqrt{5})^2}{4} + 2 \left( -\frac{15}{2} + \frac{5\sqrt{5}}{6} \right) \right)$$

$$= \left( \frac{40 - 8\sqrt{5} - (25 - 10\sqrt{5} + 5)}{4}, \frac{25 - 10\sqrt{5} + 5}{4} - 15 + \frac{5\sqrt{5}}{3} \right)$$

$$= \left( \frac{5 + \sqrt{5}}{2}, -\frac{15}{2} - \frac{5\sqrt{5}}{6} \right) = \vec{p}_1$$

(6)

∴ the orbit  $\{\vec{p}_1, \vec{p}_2\}$  is a period-2 orbit for  $f$ .

Stability

$$Df(x, y) = \begin{bmatrix} 4 - 2x & 0 \\ 2x & 2 \end{bmatrix}$$

$$Df^2(\vec{p}_1) = Df(\vec{p}_2) \cdot Df(\vec{p}_1)$$

$$= \begin{bmatrix} 4 - 2\left(\frac{5 - \sqrt{5}}{2}\right) & 0 \\ 2\left(\frac{5 - \sqrt{5}}{2}\right) & 2 \end{bmatrix} \begin{bmatrix} 4 - 2\left(\frac{5 + \sqrt{5}}{2}\right) & 0 \\ 2\left(\frac{5 + \sqrt{5}}{2}\right) & 2 \end{bmatrix}$$

$$= \begin{bmatrix} -1 + \sqrt{5} & 0 \\ 5 - \sqrt{5} & 2 \end{bmatrix} \begin{bmatrix} -1 - \sqrt{5} & 0 \\ 5 + \sqrt{5} & 2 \end{bmatrix}$$

$$= \begin{bmatrix} 1 - 5 & 0 \\ 10 - 2\sqrt{5} & 4 \end{bmatrix} = \begin{bmatrix} -4 & 0 \\ 10 - 2\sqrt{5} & 4 \end{bmatrix}$$

$$\lambda_1 = 4, \lambda_2 = -4$$

∴ the period-2 orbit is a source.

b) For  $a = \frac{1}{3}$  &  $b = 0$ , the map is

$$f(x, y) = \left( \frac{1}{3}x, x^2 + 2y \right).$$

$(0, 0)$  is a fixed point, & we wish to determine its stability:

$$Df(x, y) = \begin{bmatrix} \frac{1}{3} & 0 \\ 2x & 2 \end{bmatrix}$$

$$\therefore Df(0, 0) = \begin{bmatrix} \frac{1}{3} & 0 \\ 0 & 2 \end{bmatrix}$$

The eigenvalues are

$$\lambda_1 = \frac{1}{3}, \text{ so } |\lambda_1| < 1$$

$$\lambda_2 = 2, \text{ so } |\lambda_2| > 1$$

$\therefore$  the origin is a saddle.

3.  $f(x,y) = (ax, bx^3 + cy)$

a)  $f(0,0) = (0,0)$ ,  $\therefore (0,0)$  is a fixed point.

$$Df(x,y) = \begin{bmatrix} a & 0 \\ 3bx^2 & c \end{bmatrix} \quad \therefore Df(0,0) = \begin{bmatrix} a & 0 \\ 0 & c \end{bmatrix}$$

The eigenvalues are  $\lambda_1 = a$  &  $\lambda_2 = c$ .  $\therefore$  The origin is a saddle if

$\bullet |a| < 1$  &  $|c| > 1$

OR

$\bullet |a| > 1$  &  $|c| < 1$

b) 
$$\begin{cases} x_{n+1} = ax_n \\ y_{n+1} = bx_n^3 + cy_n \end{cases} \iff \begin{cases} x_n = \frac{1}{a} x_{n+1} \\ y_n = \frac{1}{c} (y_{n+1} - bx_n^3) \end{cases}$$

$$\iff \begin{cases} x_n = \frac{1}{a} x_{n+1} \\ y_n = \frac{1}{c} \left( y_{n+1} - \frac{b}{a^3} x_{n+1}^3 \right) \end{cases}$$

$$\therefore f^{-1}(x,y) = \left( \frac{1}{a}x, \frac{1}{c} \left( y - \frac{b}{a^3}x^3 \right) \right)$$



(9)

$$c) f(t, qt^3) = (at, bt^3 + cqt^3)$$

$$= (at, (b+qc)t^3)$$

$\therefore$  The curve  $y = qx^3$  is forward invariant if

$$(b+qc) = qa^3 \Leftrightarrow q(a^3 - c) = b$$

$$\Leftrightarrow q = \frac{b}{a^3 - c}$$

Similarly,

$$f^{-1}(t, qt^3) = \left( \frac{1}{a}t, \frac{1}{c} \left( qt^3 - \frac{b}{a^3}t^3 \right) \right)$$

$$= \left( \frac{t}{a}, \left( q - \frac{b}{a^3} \right) \frac{1}{c}t^3 \right)$$

$\therefore$  The curve  $y = qx^3$  is backward invariant if

$$\left( q - \frac{b}{a^3} \right) \frac{1}{c} = \frac{q}{a^3} \Leftrightarrow q \left( \frac{1}{c} - \frac{1}{a^3} \right) = \frac{b}{ca^3} \Leftrightarrow //$$

$$// \Leftrightarrow q(a^3 - c) = b \Leftrightarrow q = \frac{b}{a^3 - c}$$

Hence,  $S$  is invariant.

d) The eigenvectors of  $Df(0,0)$  are  $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$  and  $\begin{bmatrix} 0 \\ 1 \end{bmatrix}$ . We see that the first of these is tangent to  $S$  at the origin, and  $f^n(x, y) = (ax^n, y)$ .

$$f^n(t, yt^3) \rightarrow 0 \text{ as } n \rightarrow \infty \text{ if } |a| < 1,$$

$$f^{-n}(t, yt^3) \rightarrow 0 \text{ as } n \rightarrow \infty \text{ if } |a| > 1.$$

So  $S$  is one of the manifolds of  $f$ . The other eigenvector points along the  $y$  axis, so we test points on the  $y$  axis to see if that set is invariant:

$$f(0, y) = (0, cy) \rightarrow \text{still on the } y \text{ axis,} \\ \therefore \text{forward invariant}$$

$$f^{-1}(0, y) = (0, \frac{y}{c}) \rightarrow \text{still on the } y \text{ axis,} \\ \therefore \text{backward invariant}$$

Hence, the  $y$  axis is invariant. Also,

$$\bullet f^n(0, y) \rightarrow 0 \text{ as } n \rightarrow \infty \text{ if } |c| < 1$$

$$\bullet f^{-n}(0, y) \rightarrow 0 \text{ as } n \rightarrow \infty \text{ if } |c| > 1$$

∴ we have two cases.

$$1) |a| < 1, |c| > 1$$

$$\mathcal{S} = \{(x, qx^3) : x \in \mathbb{R}\}$$

$$\mathcal{U} = \{(0, y) : y \in \mathbb{R}\}$$

$$2) |a| > 1, |c| < 1$$

$$\mathcal{S} = \{(0, y) : y \in \mathbb{R}\}$$

$$\mathcal{U} = \{(x, qx^3) : x \in \mathbb{R}\}$$