

1. a) Require

$$i) \mathcal{L}\left(\frac{d}{ab}, \frac{a}{b}\right) = 0 \Leftrightarrow a \ln\left(\frac{a}{b}\right) - b \frac{a}{b} - \alpha b \frac{d}{ab} + d \ln\left(\frac{d}{ab}\right) + K' = 0$$

$$\Leftrightarrow a \left(\ln\left(\frac{a}{b}\right) - 1\right) + d \left(\ln\left(\frac{d}{ab}\right) - 1\right) + K' = 0$$

$$\Leftrightarrow K' = a \left(1 - \ln\left(\frac{a}{b}\right)\right) + d \left(1 - \ln\left(\frac{d}{ab}\right)\right)$$

$$iii) \dot{\mathcal{L}}(x, y) \leq 0 \Leftrightarrow \frac{a}{y} \dot{y} - b \dot{y} - \alpha b \dot{x} + \frac{d}{x} \dot{x} \leq 0$$

$$\Leftrightarrow \left(\frac{a}{y} - b\right)(\alpha b x y - d y) + \left(\frac{d}{x} - \alpha b\right)(\alpha x - b x y)$$

$$\Leftrightarrow (a - by)(\alpha b x - d) + (d - \alpha b x)(a - by) \leq 0$$

$$\Leftrightarrow 0 \leq 0 \quad \checkmark$$

ii) We know that the curves $\mathcal{L}(x, y) = C$ are concentric periodic orbits, and $\dot{\mathcal{L}} = 0$ everywhere in the 1st quadrant. So we only need to show that $\mathcal{L}(x, y)$ is strictly positive or strictly negative in the first quadrant, with the exception of the equilibrium point where $\mathcal{L}(x, y) = 0$.

Let $x = \frac{d}{ab} \cdot r$, $y = \frac{a}{b} \cdot r$. Then

$$L(x, y) = a \ln\left(\frac{ra}{b}\right) - b \frac{ra}{b} - d b \frac{d}{ab} r + d \ln\left(\frac{d}{ab} r\right) + k'$$

$$= a \ln(r) + a \ln\left(\frac{a}{b}\right) - ar$$

$$- dr + d \ln(r) + d \ln\left(\frac{d}{ab}\right) + k'$$

$$= a \ln(r) + d \ln(r)$$

$$+ a \left(\cancel{\ln\left(\frac{a}{b}\right)} - r \right) + d \left(\cancel{\ln\left(\frac{d}{ab}\right)} - r \right)$$

$$+ a \left(1 - \cancel{\ln\left(\frac{a}{b}\right)} \right) + d \left(1 - \cancel{\ln\left(\frac{d}{ab}\right)} \right)$$

$$= a \ln(r) - ar + d \ln(r) - dr + a + d$$

$$= a (\ln(r) - r + 1) + d (\ln(r) - r + 1)$$

$$= (a+d) (\ln(r) - r + 1) < 0 \quad \forall r > 0, r \neq 1$$

$\therefore \mathcal{L}(x, y) < 0 \neq x > 0 \text{ \& } y > 0$, except at the equilibrium point.

$\therefore \mathcal{L}(x, y)$ is a Lyapunov function for the coexistence steady state of (1) if

$$K' = a \left(1 - \ln\left(\frac{a}{b}\right)\right) + d \left(1 - \ln\left(\frac{d}{ab}\right)\right).$$

b) i) $\mathcal{L}_1\left(\frac{d}{ab}, \frac{a}{b}\right) = 0$, so \mathcal{L}_1 satisfies this requirement

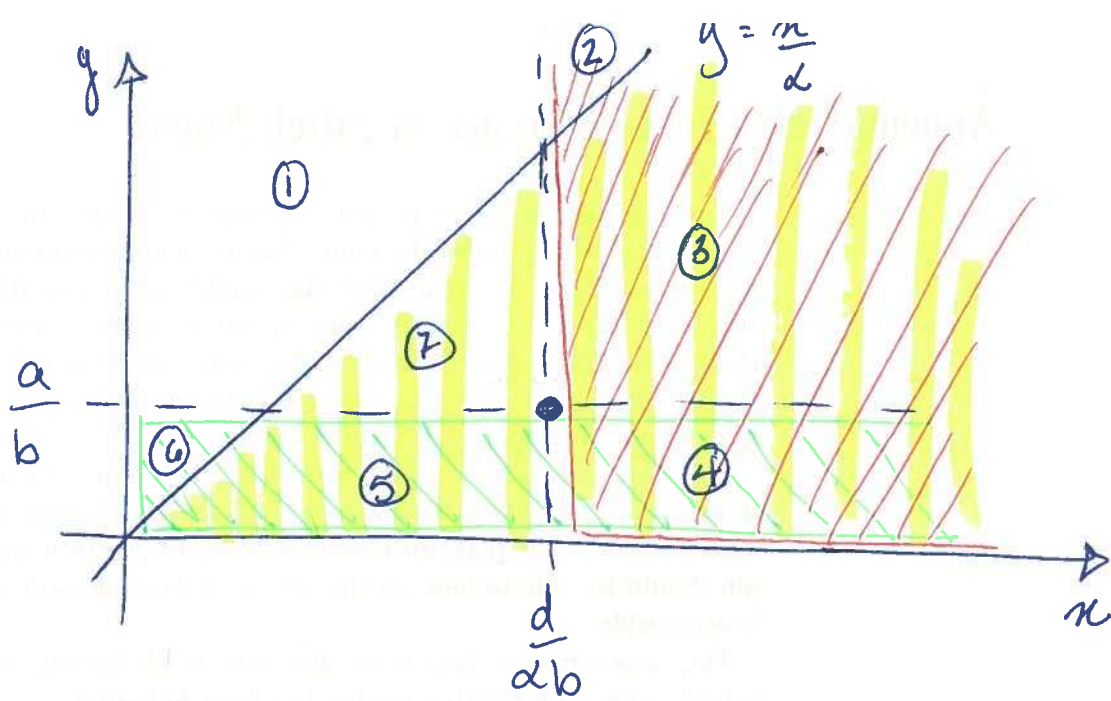
ii) $\mathcal{L}_1(x, y) > 0 \neq (x, y) \neq \left(\frac{b}{ad}, \frac{a}{b}\right)$, so \mathcal{L}_1 satisfies this requirement

$$\text{iii) } \dot{\mathcal{L}}_1(x, y) = 2 \left(x - \frac{d}{ab}\right) (ax - bxy) + 2 \left(y - \frac{a}{b}\right) (dby - dy)$$

$$= \frac{2}{ab} (dbx - d) (ax - bxy) + \frac{2}{b} (by - a) (dby - d)$$


$$= \frac{2x}{ab} (dbx - d) (a - by) + \frac{2y}{b} (by - a) (dbx - d)$$

$$= \frac{2}{b} \left(\frac{x}{a} - y\right) \left[\underline{(dbx - d)} \underline{(a - by)} \right]$$



 = $a - by > 0$

 = $\alpha b x - d > 0$

 = $\frac{x}{d} - y > 0$

\therefore in regions ①, ③, ⑤, and ⑥, $\alpha_1(x, y) < 0$. In the remaining regions, $\alpha_1(x, y) > 0$, and so $\alpha_1(x, y)$ is NOT a Lyapunov function for the coexistence steady state of (1).

2. a) The phase plane equation is

$$\frac{\dot{y}}{y} = \left(\frac{ay^2}{x} - y \right) \frac{1}{ayx - x^2} \quad \text{or } \frac{1}{y}$$

$$\frac{1}{y} \Rightarrow \frac{dy}{dx} = \frac{y}{x} (ay - x) \frac{1}{x(ay - x)}$$

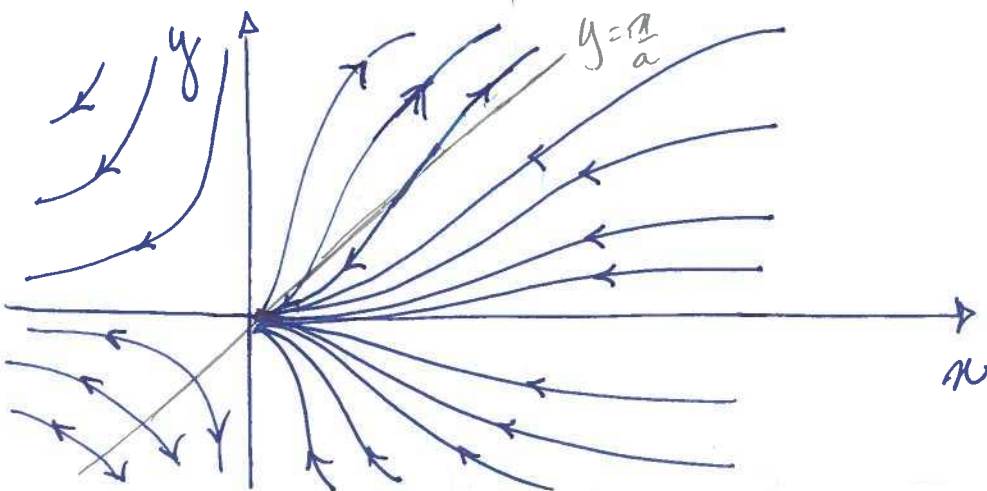
$$\Rightarrow \frac{dy}{y} = \frac{y}{x^2}, \quad ay - x \neq 0$$

$$\Rightarrow \int \frac{1}{y} dy = \int \frac{1}{x^2} dx, \quad ay - x \neq 0$$

$$\Rightarrow \ln|y| = -\frac{1}{x} + \tilde{K}, \quad x \neq ay$$

$$\Rightarrow |y| = K e^{-\frac{1}{x}}, \quad x \neq ay$$

$$\Rightarrow y = \pm K e^{-\frac{1}{x}}, \quad x \neq ay$$



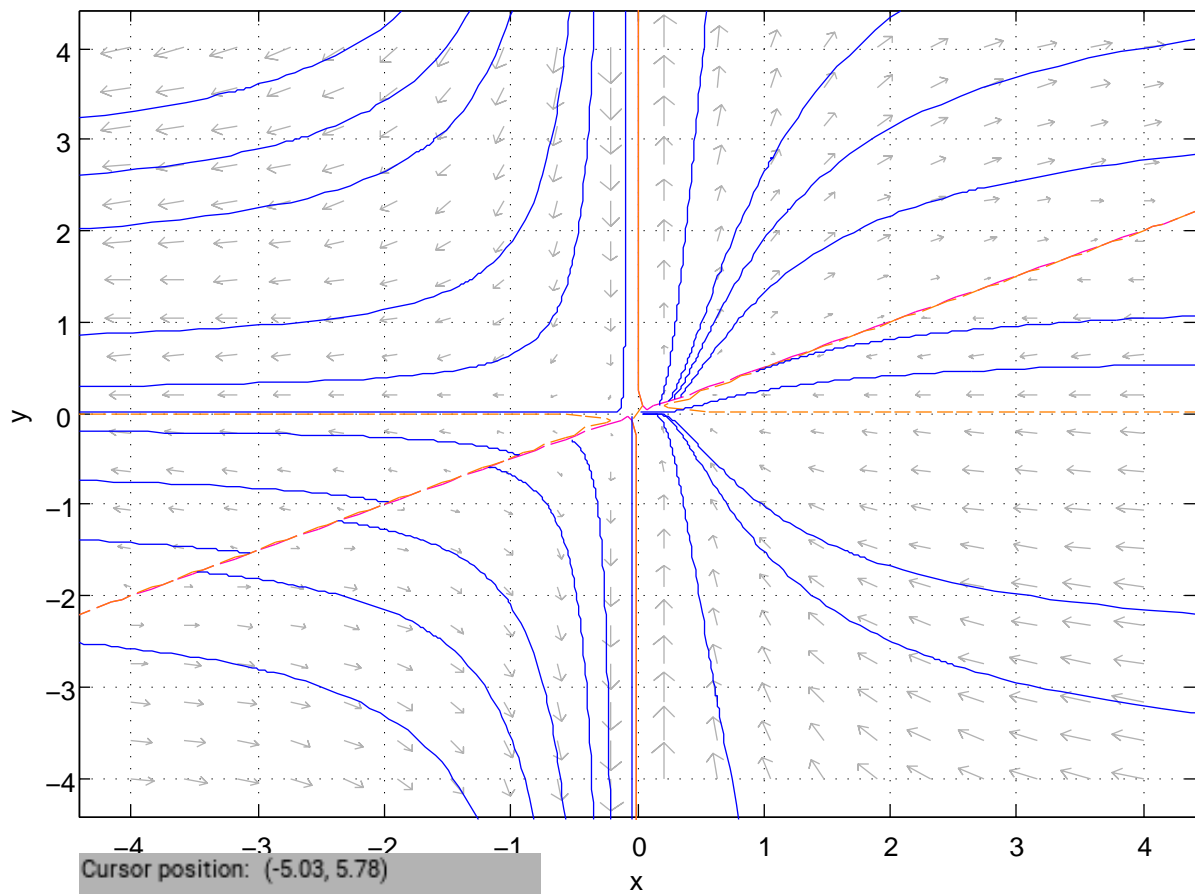
, $x_0 \neq 0$

(see phase plane next p.)

$$x' = x(a y - x)$$

$$y' = y(a y - x)/x$$

a = 2



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Cursor position: (-5.03, 5.78)

The backward orbit from (-3.1, 3.5) left the computation window.
 Ready.
 The forward orbit from (-4.1, -1.4) left the computation window.
 The backward orbit from (-4.1, -1.4) → a possible eq. pt. near (-3.1, -1.5).
 Ready.

(7)

Note: flow direction along these curves is determined by looking at \dot{x} & \dot{y} .

$$3. \begin{cases} \dot{x} = x - 3y - 4 \\ \dot{y} = x^2 + 4y \end{cases}$$

a) Steady states:

$$\begin{cases} \dot{x} = 0 \\ \dot{y} = 0 \end{cases} \Leftrightarrow \begin{cases} x - 3y - 4 = 0 \\ x^2 + 4y = 0 \end{cases} \Leftrightarrow \begin{cases} y = \frac{1}{3}x - \frac{4}{3} \\ y = -\frac{1}{4}x^2 \end{cases}$$

Combining, we obtain:

$$\frac{1}{3}x - \frac{4}{3} = -\frac{1}{4}x^2 \Leftrightarrow 4x - 16 = -3x^2 \Leftrightarrow (1)$$

$$(1) \Leftrightarrow 3x^2 + 4x - 16 = 0 \Leftrightarrow x = \frac{-2 \pm \sqrt{4 + 48}}{3}$$

$$\Leftrightarrow x = \frac{-2 \pm \sqrt{52}}{3} = \frac{-2 \pm 2\sqrt{13}}{3} = \frac{2}{3}(-1 \pm \sqrt{13})$$

$$\text{and } y = \frac{2}{3}(-1 \pm \sqrt{13}) - \frac{4}{3} = \frac{-14 \pm 2\sqrt{13}}{3} = \frac{2}{9}(-7 \pm \sqrt{13})$$

\therefore There are two steady states:

$$ss1 = \left(\frac{2}{3}(-1 + \sqrt{13}), \frac{2}{9}(-7 + \sqrt{13}) \right) \text{ and } \left(\frac{2}{3}(-1 - \sqrt{13}), \frac{2}{9}(-7 - \sqrt{13}) \right) = ss2$$

To classify these steady states, we find the eigenvalues of the Jacobian:

$$J = \begin{bmatrix} 1 & -3 \\ 2x & 4 \end{bmatrix}$$

@ ssl:

$$(J - \lambda I) = 0 \Leftrightarrow \begin{vmatrix} 1-\lambda & -3 \\ \frac{4}{3}(-1+\sqrt{13}) & 4-\lambda \end{vmatrix} = 0$$

$$\Leftrightarrow \lambda^2 - 5\lambda + 4 + 4(-1+\sqrt{13}) = 0$$

$$\Leftrightarrow \lambda^2 - 5\lambda + 4\sqrt{13} = 0$$

$$\Leftrightarrow \lambda = \frac{5 \pm \sqrt{25 - 16\sqrt{13}}}{2}$$

$\Leftrightarrow \lambda_1, \lambda_2$ are complex conjugates w/ +ve real part

\therefore ssl is an unstable focus.

@ ss 2:

$$|J - \lambda I| = 0 \Leftrightarrow \begin{vmatrix} 1 - \lambda & -3 \\ \frac{4}{3}(-1 - \sqrt{13}) & 4 - \lambda \end{vmatrix} = 0$$

$$\Leftrightarrow \lambda^2 - 5\lambda + 4 + 4(-1 - \sqrt{13}) = 0$$

$$\Leftrightarrow \lambda^2 - 5\lambda - 4\sqrt{13} = 0$$

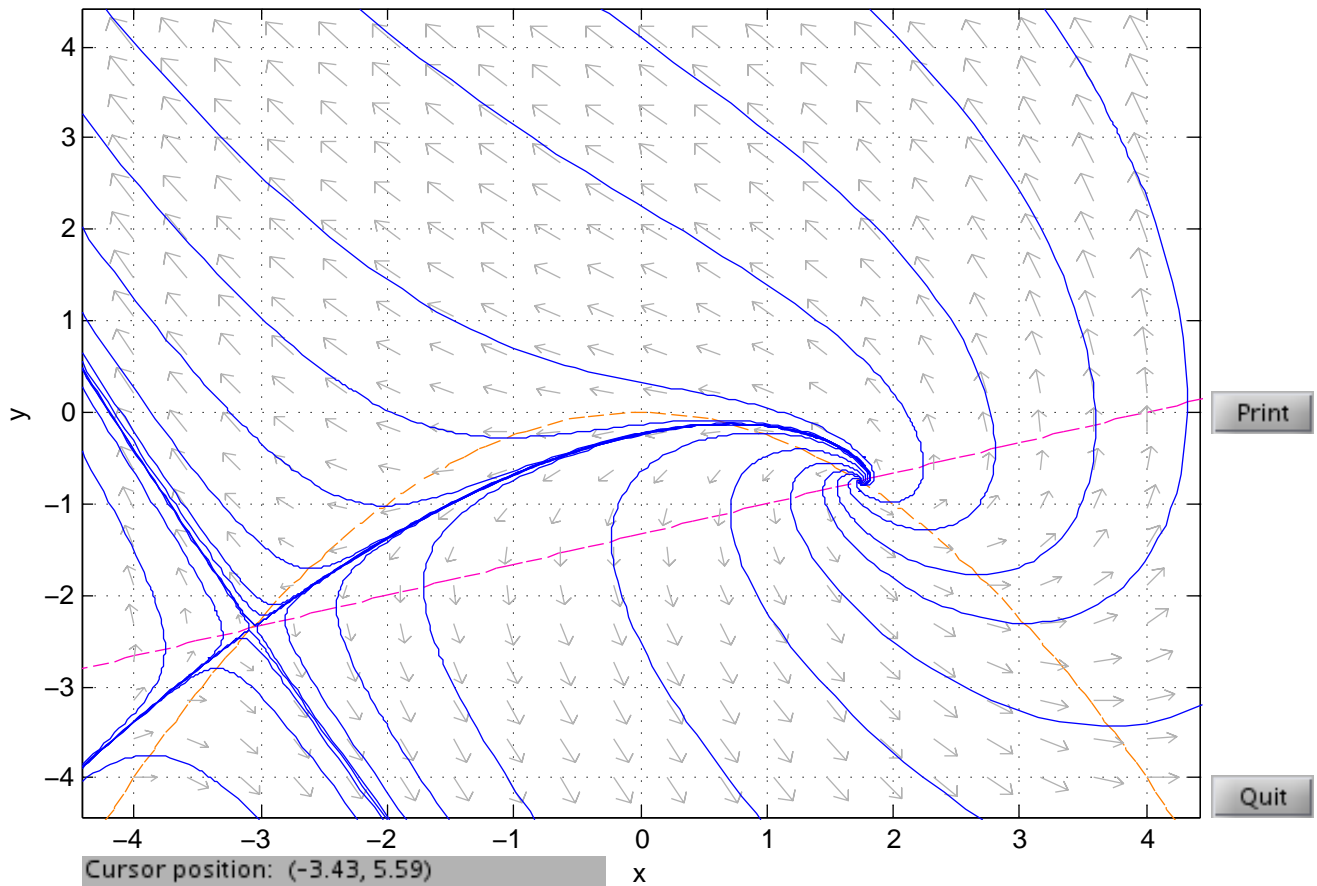
$$\Leftrightarrow \lambda = \frac{5 \pm \sqrt{25 + 16\sqrt{13}}}{2}$$

$$\Leftrightarrow \lambda_1 > 0 + \lambda_2 < 0$$

\therefore ss 2 is a saddle node.

See phase plane next page.

$$\begin{aligned}x' &= x - 3y - 4 \\ y' &= x^2 + 4y\end{aligned}$$



The backward orbit from $(-3.1, -2.5)$ left the computation window.
Ready.
The forward orbit from $(-3, -2.4)$ left the computation window.
The backward orbit from $(-3, -2.4) \rightarrow$ a possible eq. pt. near $(1.7, -0.75)$.
Ready.