

Math 339 - Fall 2019
A#5 - Solutions

$$1. \begin{cases} \dot{x} = y \\ \dot{y} = -x - x^3 \end{cases}$$

$$a) J \Big|_{(0,0)} = \begin{bmatrix} 0 & 1 \\ -1-3x^2 & 0 \end{bmatrix} \Big|_{(0,0)} = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$$

Eigenvalues:

$$(-\lambda)^2 + 1 = 0 \Leftrightarrow \lambda^2 + 1 = 0 \Leftrightarrow \lambda = \pm i$$

\therefore the steady state is a centre, from a linear analysis, so we don't know if, in the full model, the steady state is stable or unstable.

b) This is a Hamiltonian system, so we can use total energy as our Lyapunov function. We have

$$E = \frac{1}{2} y^2 + P(x)$$

where

$$\frac{dP}{dx} = -\dot{x} = -y = x + x^3 \Leftrightarrow (1) \Leftrightarrow P(x) = \frac{x^2}{2} + \frac{x^4}{4}$$

$$\therefore E = \frac{1}{2} y^2 + \frac{2x^2 + x^4}{4} \quad \cdot \quad \cdot \quad \cdot \quad (1)$$

Taking (1) as our Lyapunov function we have:

$$\begin{aligned} E(0,0) &= 0 && \text{as required} \\ E(x,y) &> 0 && \forall (x,y) \neq (0,0) \text{ as required} \end{aligned}$$

Using $E(x,y)$ we find that

$$\begin{aligned} \dot{E}(x,y) &= y\dot{y} + x\dot{x} + x^3\dot{x} \\ &= y(-x-x^3) + xy + x^3y \\ &= 0 \end{aligned}$$

and so the $(0,0)$ steady state is indeed a centre and solution trajectories are the level curves of $E(x,y)$.

$$2. \begin{cases} \dot{x} = -z + \left(\frac{x^3}{3} - x\right) \\ \dot{z} = x \end{cases} \dots (1)$$

a) Consider $W(x,z) = x^2 + z^2$. We observe that the system (1) has a steady state at

$$\dot{z} = 0 \Leftrightarrow x = 0 \quad \therefore \dot{x} = 0 \Leftrightarrow z = 0$$

So the only steady state is at $(0,0)$.

$$\begin{aligned} W(0,0) &= 0 \\ W(x,z) &> 0 \quad \forall (x,z) \neq (0,0) \end{aligned}$$

Now consider \dot{W} .

③

$$\begin{aligned}\dot{W} &= \frac{\partial W}{\partial x} \dot{x} + \frac{\partial W}{\partial z} \dot{z} = 2xz \dot{x} + 2z \dot{z} \\ &= 2x(-z + (\frac{x^3}{3} - x)) + 2z x \\ &= -2xz + \frac{2x^2}{3}(x^2 - 3) + 2xz \\ &= \frac{2x^2}{3}(x^2 - 3)\end{aligned}$$

$\therefore W(x, z)$ is a Lyapunov function for (1) if $x^2 < 3 \Leftrightarrow |x| < \sqrt{3}$. \therefore The level curves of $W(x, z)$ are circles, we obtain the result that $W(x, z)$ is a Lyapunov function for (1) in the disc $(x^2 + z^2 < 3)$.

b) The Lyapunov function tells us that all starting points in the disc

$$D = \{(x, z) \in \mathbb{R}^2 \mid x^2 + z^2 < 3\}$$

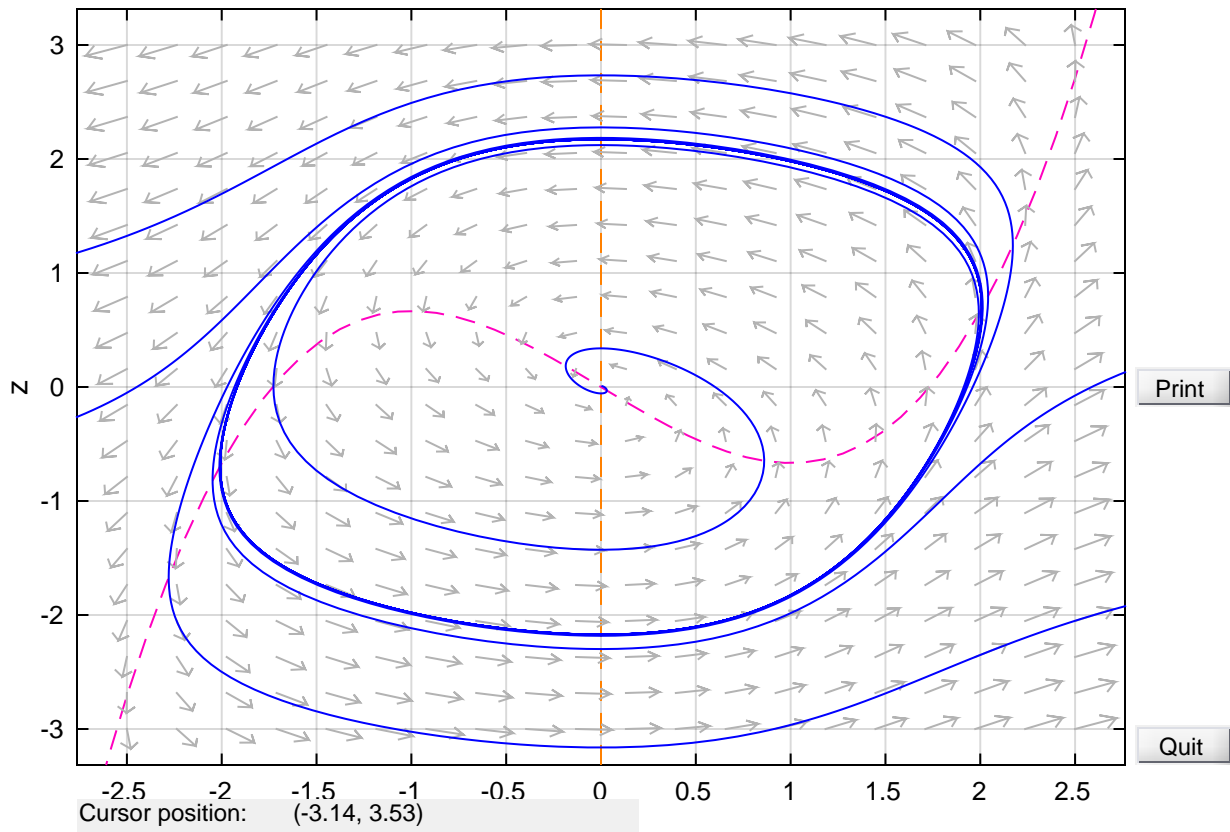
have ω -limit set $(0, 0)$ + so the region D is contained in the basin of attraction of $(0, 0)$.

c) From (b) we know that $(0, 0)$ is ~~the~~ the ω -limit set of (1) for all starting points in D . $\therefore (0, 0)$ is the α -limit set of the backwards system (3) for all starting points in D .

(The phase plane on the next page shows that D is indeed a subset of the basin of attraction of $(0, 0)$, which is bounded by an unstable limit cycle which is not a circle & is larger than ∂D .)

$$x' = -z + (x^3/3 - x)$$

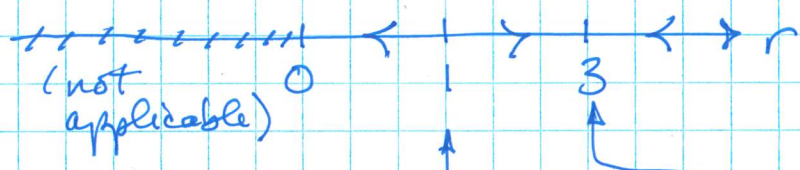
$$z' = x$$



The backward orbit from $(1.7, 2.3)$ --> a nearly closed orbit.
 Ready.
 The forward orbit from $(-2.4, 0.061)$ left the computation window.
 The backward orbit from $(-2.4, 0.061)$ --> a nearly closed orbit.
 Ready.

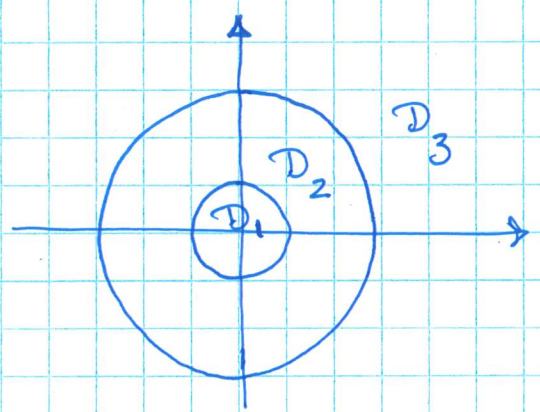
$$3. \begin{cases} \dot{r} = r(r-1)(3-r) \dots (3) \\ \dot{\theta} = 1 \end{cases}$$

Steady state: $(0,0)$
 limit cycle: $r=1, r=3$, with flow:



the limit cycle at $r=1$ is unstable

the limit cycle at $r=3$ is stable

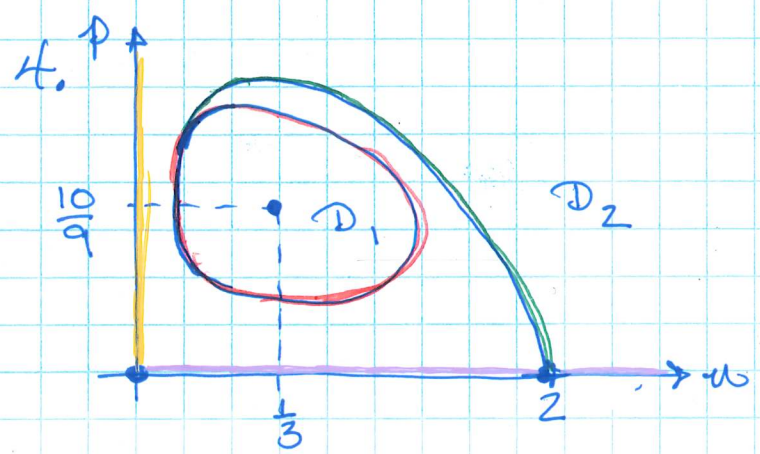


$$D_1 = \{(r, \theta) \mid r < 1\}$$

$$D_2 = \{(r, \theta) \mid 1 < r < 3\}$$

$$D_3 = \{(r, \theta) \mid r > 3\}$$

- \forall starting points in D_1 , the ω -limit set is $(0,0)$.
- \forall starting points in $D_2 \cup D_3 \cup \{(r, \theta) \mid r=3, \theta \in \mathbb{R}\}$, the ω -limit set is $r=3, \theta \in \mathbb{R}$.
- for $r_0 = 1$, the ω -limit set $\omega(c) = \{$



- = the limit cycle, D_2
- = the unstable manifold of $(2,0)$, D_u
- = the stable manifolds of $(2,0)$, D_s
- = the stable manifold of $(0,0)$, D_E

w-limit sets

that are not steady states and

\forall starting points not on D_E or D_S , the w -limit set is D_L
 " " " on D_E , the w -limit set is $(0,0)$
 " " " on D_S , " " " " $(2,0)$

α -limit sets

\forall starting points not on D_u or D_s where $n \leq 2$, outside D_L ,
 and not at a steady state, the α -limit set is \emptyset
 \forall starting points on D_s where $n \leq 2$, the α -limit set is $(0,0)$
 \forall " " " " D_u , the α -limit set is $(2,0)$
 \forall " " " inside D_L , the α -limit set is $(\frac{1}{3}, \frac{10}{9})$

Steady States

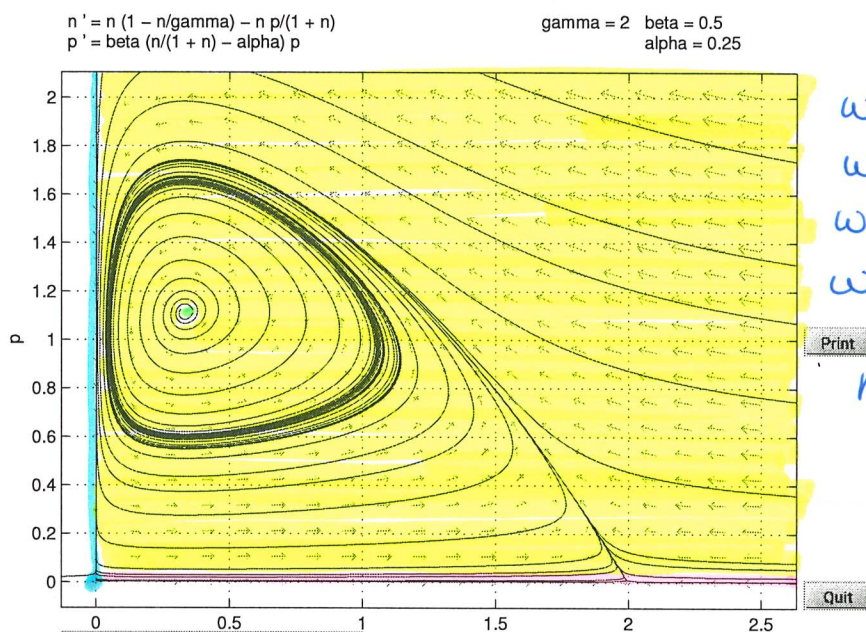
Note that $w(n^*, p^*) = \alpha(n^*, p^*)$ for each of the three steady states $(n^*, p^*) = (0,0); (2,0); (\frac{1}{3}, \frac{10}{9})$.

Also, $w(D_L) = \alpha(D_L)$.

6b

4. - illustrated
w-limit sets

Figure 1: Figure for question # 4.



$w(\text{yellow}) = \text{limit cycle}$
 $w(\text{blue dot}) = (0,0)$
 $w(\text{cyan}) = (0,0)$
 $w(\text{pink}) = (2,0)$

Note: $\bullet = (0,0)$

$$w(n,p) = \{ \text{limit cycle} \} \cup \left\{ (n,p) \mid n \neq 0, p \neq 0 \wedge (n,p) \neq \left(\frac{1}{3}, \frac{10}{9} \right) \right\}$$

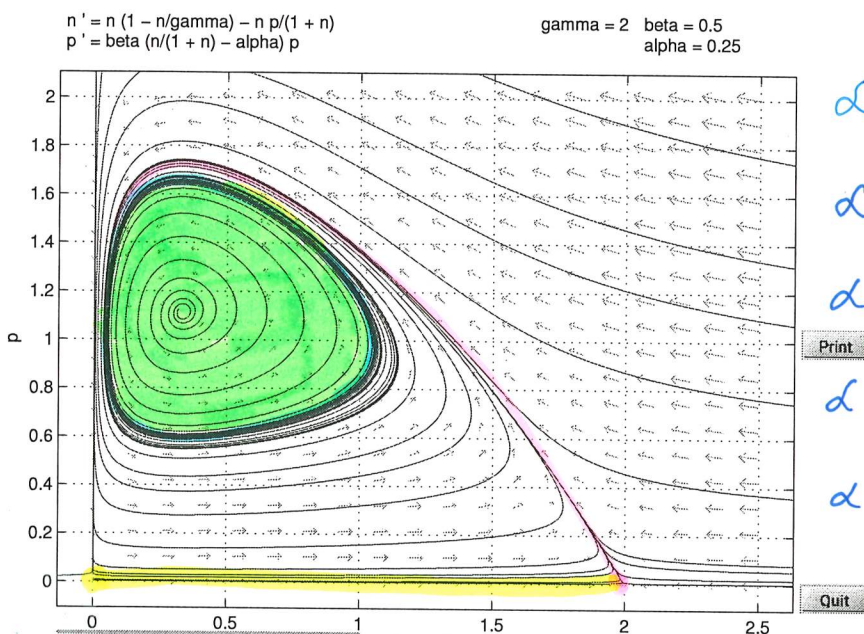
$$w(0,p) = \{(0,0)\} \quad \forall p \geq 0$$

$$w(n,0) = \{(2,0)\} \quad \forall n > 0$$

$$w\left(\frac{1}{3}, \frac{10}{9}\right) = \left(\frac{1}{3}, \frac{10}{9}\right)$$

α - limit sets

Figure 1: Figure for question # 4.



$\alpha(\text{green}) = \text{green} \text{ (limit cycle)}$

$\alpha(\text{light green}) = (\frac{1}{3}, \frac{10}{9})$

$\alpha(\text{pink}) = (2, 0)$

$\alpha(\text{yellow}) = (0, 0)$

$\alpha(\text{white}) = \emptyset$
 ↑
 no highlighting

$\alpha(n, p) = \emptyset \quad \forall \{n, p\}$

not on the unstable manifold of $(2, 0)$, outside the limit cycle & not on the unstable manifold of $(0, 0)$

$\alpha(n, 0) = (0, 0) \quad \forall n < 2$

$\alpha(n, p) = (2, 0) \quad \forall \{n, p\} \text{ on the unstable manifold of } (2, 0)$

$\alpha(n, p) = \text{limit cycle} \quad \forall \{n, p\} \text{ on the limit cycle}$

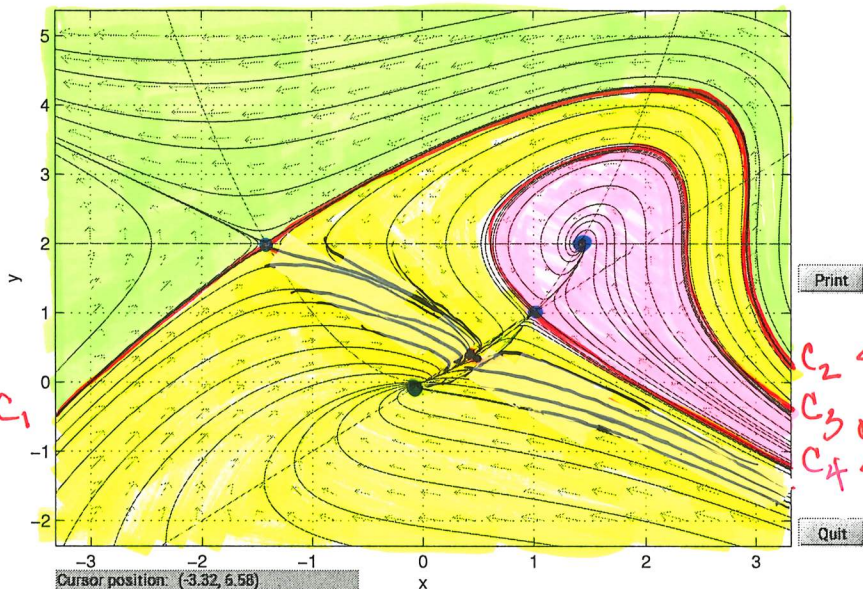
$\alpha(n, p) = (\frac{1}{3}, \frac{10}{9}) \quad \forall \{n, p\} \text{ inside the limit cycle}$

5.

Figure 2: Figure for question # 5.

$$x' = (x - y)(y - 2)$$

$$y' = x^2 - y$$



Stable manifold of $(-\sqrt{2}, 2)$ $\rightarrow C_1$

stable manifold of $(-\sqrt{2}, 2)$ $\leftarrow C_2$

stable manifolds of $(1, 1)$ $\leftarrow C_3, C_4$

The backward orbit from (0.89, 1) left the computation window.
Ready.
The forward orbit from (0.94, 0.81) \rightarrow a possible eq. pt. near $(-1.3e-10, -1.1e-10)$.
The backward orbit from (0.94, 0.81) left the computation window.
Ready.

Note that the stable manifolds form the boundaries of the basins of attraction (regions in pink, yellow, & green highlighting).

The ω -limit set for		is \emptyset
" " " " "		is $(0, 0)$
" " " " "		is $(\sqrt{2}, 2)$
" " " " "	C_1	is $(-\sqrt{2}, 2)$
" " " " "	C_2	is $(-\sqrt{2}, 2)$
" " " " "	C_3	is $(1, 1)$
" " " " "	C_4	is $(1, 1)$

The steady state $(-\sqrt{2}, 2)$ is the $(\alpha - \epsilon)$ ω -limit set for $(\sqrt{2}, 2)$.
 " " " $(+\sqrt{2}, 2)$ " " (") " " " $(\sqrt{2}, 2)$.
 " " " $(0, 0)$ " " (") " " " $(0, 0)$.
 " " " $(1, 1)$ " " (") " " " $(1, 1)$.