

7.6 Lyapunov Functions

Lyapunov functions: Alexander Mikhailovich Lyapunov (Russian)

The Lyapunov function is a generalisation of the energy function we discussed last time.

Energy function:

- is minimum (has minima) at the stable or steady states
- if there is dissipation, $\dot{E} < 0$ in the basin of attraction of the steady state
- is constant along phase plane trajectories if there is no dissipation

7.22

~~Let \vec{x}^* be an equilibrium of $\dot{\vec{x}} = \vec{f}(\vec{x})$. If there exists a Lyapunov function for \vec{x}^* , then \vec{x}^* is stable. If~~

Def 7.22

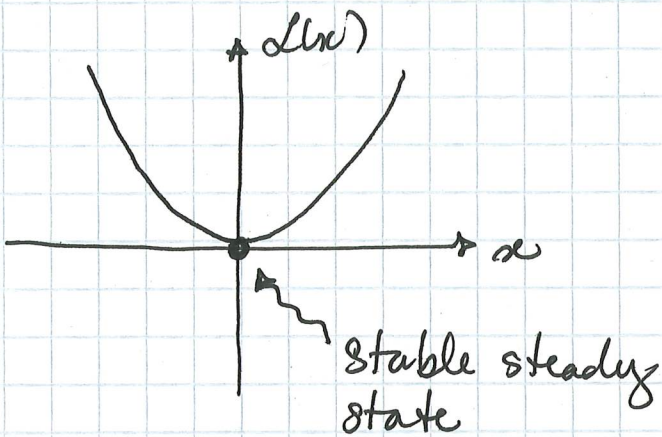
Let \vec{x}^* be an equilibrium of $\dot{\vec{x}} = \vec{f}(\vec{x})$. A function $\mathcal{L}: \mathbb{R}^n \rightarrow \mathbb{R}$ is called a Lyapunov function for \vec{x}^* if for some neighbourhood W of \vec{x}^* , the following conditions are satisfied:

1. $\mathcal{L}(\vec{x}^*) = 0$, and $\mathcal{L}(\vec{x}) > 0 \forall \vec{x} \neq \vec{x}^*$ in W ,
2. $\dot{\mathcal{L}}(\vec{x}) \leq 0 \forall \vec{x}$ in W .

If the stronger inequality

$$2'. \dot{\mathcal{L}}(\vec{x}) < 0 \forall \vec{x} \text{ in } W$$

holds, then \mathcal{L} is called a strict Lyapunov fu.



Ex 2: pendulum from last time

Show that for each even integer n , the total energy

$$E(x, y) = \frac{1}{2} y^2 + 1 - \cos(x)$$

is a Lyapunov function for the equilibria $(n\pi, 0)$ of

$$\begin{cases} \dot{x} = y \\ \dot{y} = -\sin(x) \end{cases}$$

Ans

$$1. E(n\pi, 0) = \frac{1}{2} (0)^2 + 1 - \cos(n\pi) = 0 + 1 - 1 = 0 \checkmark$$

$$E(x, y) \geq 0 \quad \forall x \neq n\pi \quad \checkmark$$

↑
even

$$2. \dot{E}(x, y) = 0 \quad \forall (x, y) \in \mathbb{R}^2$$

$\therefore E(x, y)$ is a Lyapunov function for each steady state $(n\pi, 0)$, n even.

Theorem 7.23

Let \vec{x}^* be an equilibrium of $\dot{\vec{x}} = \vec{f}(\vec{x})$. If there exists a Lyapunov function for \vec{x}^* then \vec{x}^* is stable. If there exists a strict Lyapunov function for \vec{x}^* , then \vec{x}^* is asymptotically stable.

(pf: Hirsch & Smale, 1974)

Ex 3

Show that $E(x) = x^2$ is a strict Lyapunov fu for the equilibrium $x=0$ in $\dot{x} = -x^3$.

First, consider a linear analysis

$$\dot{x} = f(x) = -x^3 \quad \text{linearised: } \dot{x} = f'(0) x = -3x^2 \cdot x = 0$$

So the linear analysis is inconclusive. Now we use Lyapunov function analysis. Using $E(x) = x^2$ we check conditions 1+2 of Def 7.22.

1. $E(0) = 0 \checkmark$ $E(x) > 0 \forall x \neq 0 \checkmark$
2. $\dot{E} = 2x\dot{x} = 2x(-x^3) = -2x^4 < 0 \forall x \neq 0$

$\therefore E(x)$ is a strict Lyapunov function for $x^* = 0$ & by Thm 7.23 we know that $x^* = 0$ is asymptotically stable (a.s.).

Ex 4

Let

$$\begin{cases} \dot{x} = -x^3 + xy \\ \dot{y} = -y^3 - x^2 \end{cases} \quad (1)$$

Prove that $(0,0)$ is an a.s.e. of (1).

Try $\mathcal{L}(x,y) = x^2 + y^2$.

1. $\mathcal{L}(0,0) = 0$, $\mathcal{L}(x,y) > 0 \quad \forall (x,y) \neq (0,0)$

2. $\dot{\mathcal{L}}(x,y) = 2x\dot{x} + 2y\dot{y}$

$$= 2x(-x^3 + xy) + 2y(-y^3 - x^2)$$

$$= -2x^4 + 2x^2y - 2y^4 - 2x^2y$$

$$= -2(x^4 + y^4) < 0 \quad \forall (x,y) \neq (0,0)$$

$\therefore \mathcal{L}(x,y) = x^2 + y^2$ is a strict Lyapunov fn for $(0,0)$
and the equilibrium is a.s.

Def 7.24

Let \vec{x}^* be an a.s.e. of $\dot{\vec{x}} = \vec{f}(\vec{x})$. Then the basin of attraction of \vec{x}^* , denoted $B(\vec{x}^*)$, is the set of initial conditions \vec{x}_0 such that

$$\lim_{t \rightarrow \infty} \vec{F}(t, \vec{x}_0) = \vec{x}^*$$

Note: Any set W on which E is a strict Lyapunov function for \vec{x}^* will be a subset of $B(\vec{x}^*)$.

Def 7.25

A set $U \subset \mathbb{R}^n$ is called a forward invariant set for $\dot{\vec{x}} = \vec{f}(\vec{x})$ if for each $\vec{x}_0 \in U$, the forward orbit $\{\vec{F}(t, \vec{x}_0) : t \geq 0\}$ is contained in U . A forward invariant set that is bounded is called a trapping region. We also require that a trapping region be an n -dimensional set.

Trapping region: weaker notion of containment than $B(\vec{x}^*)$.